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# Using the 8049 as an 80 Column Printer Controller

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## USING THE 8049 AS AN 80 COLUMN PRINTER CONTROLLER

### I. INTRODUCTION

This Application Note details using INTEL's 8049 microcomputer as a dot matrix printer controller. Previous INTEL Application notes, (e.g. AP-27 and AP-54) described using intelligent processors and peripherals to control single printer mechanisms. This Application note expands upon the theme established in these prior notes and extends the concept to include a complete bi-directional 80 column printer using a single line buffer. For convenience this application note is divided into six sections:

1. INTRODUCTION
2. PRINT MECHANISM DESCRIPTION
3. INTERFACE CIRCUITRY
4. SOFTWARE
5. CONCLUSION
6. APPENDIX

Over the last few years 80 column output devices have become somewhat of a defacto output standard for business and some data processing applications. It should be mentioned that by no means is the 80 column format a "new" standard. 80 column computer cards have been around for more than 20 years and perhaps the existence of these cards in the early days of computers is why the 80 column format is a standard today.

Many CRT terminals use the 80 by N format and to complement this a number of printers use this same format. One reason, aside from those historic in nature, for the 80 column standard is that 80 columns of 12 pitch text on standard typewritten 8.5 inch by 11 inch paper completely fills up an entire line and allow ample room for margins. So, the 80 column format is an aesthetically convenient format.

Printers are usually divided into either impact or non-impact and a character or line oriented device. Impact printers actually use some type of "striker" to place ink on the paper. More often than not the ink is contained on a ribbon which is placed between the striker and the paper. Non-impact printers use some means other than direct pressure to place the characters on the paper. This type of printer is very fast because there is very little mechanical motion associated with placing the characters on the paper. However, because the paper is required to be treated with a special substance, it is not as convenient as an impact printer.

Character printers are capable of printing one character at a time. (Any standard home typewriter is in effect a character printer.) Line printers must print an

entire line at a time. Line printers are usually quite a bit faster than character printers, but they usually don't offer the print quality of character printers.

In recent years, the "computer boom" has caused the price of printers to tumble markedly. High volume production, competition, and the tremendous demand for reliable print mechanisms have all contributed to the decrease in price. Because of their simplicity, line printer mechanisms have decreased in price faster than other mechanisms. Therefore, when high quality print is not needed, a line printer is a very attractive choice.

This application note describes how to control an 80 column impact-line printer with an 8049/8039. The complete software listing is included in the appendix. The 8049 is the high-performance member of the MCS-48™ microcontroller family. The Processor has all of the features of the 8048 plus twice the amount of program and data memory and an 11MHz clock speed. For details about the 8049, please refer to the MCS-48 user's manual.

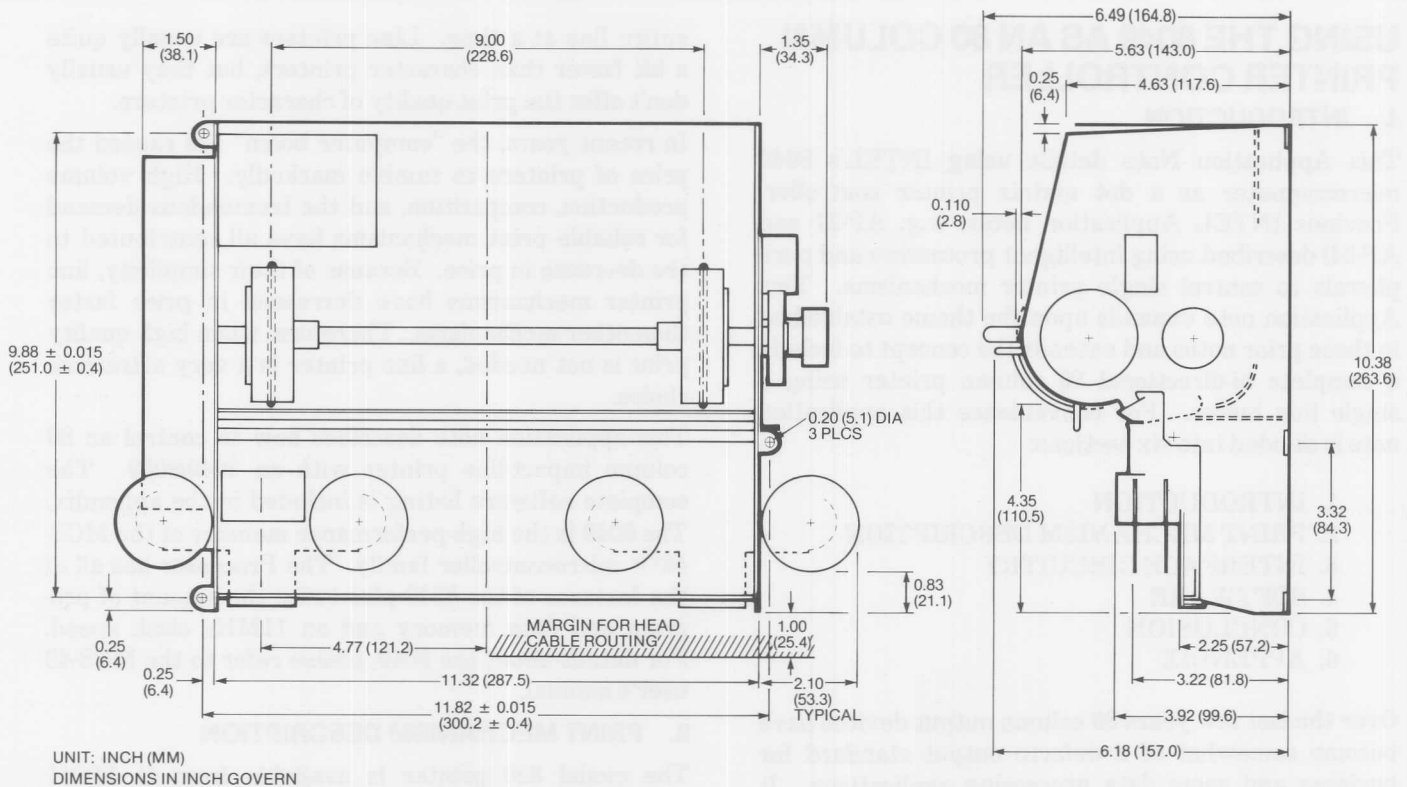
### II. PRINT MECHANISM DESCRIPTION

The model 820 printer is available from C. ITOH ELECTRONICS (5301 BEETHOVEN STREET, LOS ANGELES, CA 90066). This inexpensive and simple printer is ideal for applications requiring 80 columns of dot matrix alpha-numeric information.

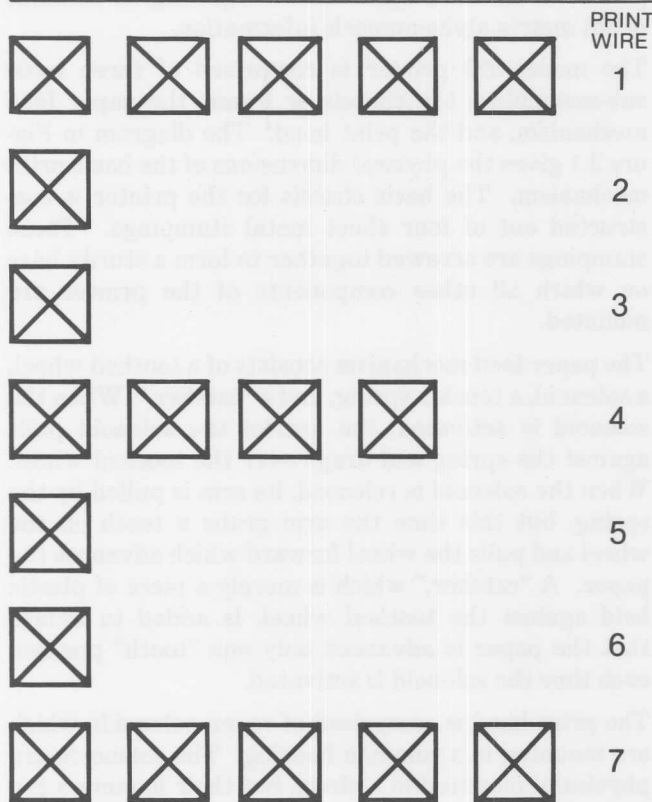
The model 820 printer is comprised of three basic sub-assemblies; the chassis or frame, the paper feed mechanism, and the print head. The diagram in Figure 2.1 gives the physical dimensions of the basic print mechanism. The basic chassis for the printer is constructed out of four sheet metal stampings. These stampings are screwed together to form a sturdy base on which all other components of the printer are mounted.

The paper feed mechanism consists of a toothed wheel, a solenoid, a tension spring, and a "catcher." When the solenoid is activated, the arm of the solenoid pulls against the spring and drags over the toothed wheel. When the solenoid is released, its arm is pulled by the spring, but this time the arm grabs a tooth on the wheel and pulls the wheel forward which advances the paper. A "catcher," which is merely a piece of plastic held against the toothed wheel, is added to assure that the paper is advanced only one "tooth" position each time the solenoid is activated.

The print head is comprised of seven solenoids which are mounted in a common housing. The solenoids are physically mounted in a circle, but their hammers are positioned linearly along the vertical axis. These seven vertically positioned hammers are the strikers that actually do the printing.



**Figure 2.1 Physical Dimensions of C. ITOH Model 820 Printer**



**Figure 2.2 "Formation" of a Character by a Dot Matrix Printer**

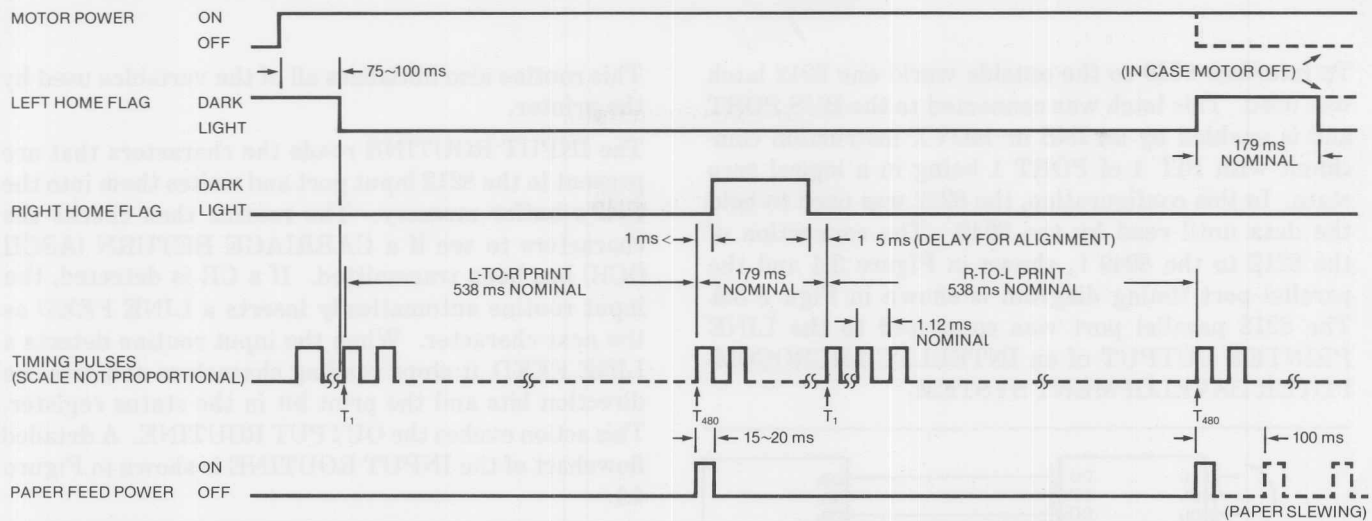
A motor, mounted toward the back of the print mechanism, drives a rubber toothed belt which turns a roller guide. A motor turns a guide that moves the print head from right to left and left to right. By properly timing the current flow through the solenoids while the print head is moving across the paper, characters can be formed. Figure 2.2 illustrates how the dot matrix printer "forms" its characters.

The timing pulses for the print head mechanism are generated by an opto-electronic sensor. This sensor, located on the left side plate of the printer, informs the print controller when to apply current to the print head mechanism. This "on-board timing wheel" assures that all characters will be properly spaced and that they will all be "in-line" in a vertical sense.

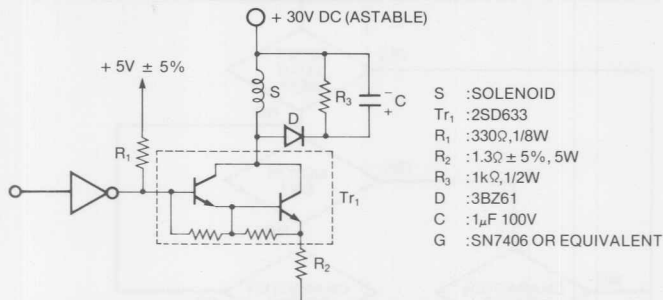
The print mechanism is also equipped with two additional sensors. These are the left home position sensor, located near the left front of the mechanism, and the right home position sensor, located near the right front of the print mechanism. These sensors simply tell the controller when the print head is in either the left or right home position. A complete timing chart for the printer is shown in Figure 2.3.

### III. INTERFACE CIRCUITRY

The manual supplied with the printer recommends some specific interface circuitry. For the most part the circuitry used in this Application Note followed these suggestions. The circuitry needed to drive the print head solenoid is shown in Figure 3.1. This same



**Figure 2.3 Timing Diagram of C. ITOH Model 820 Printer**



**Figure 3.1 Solenoid Drive Circuit (Eliminate R2 for Line Feed Solenoid)**

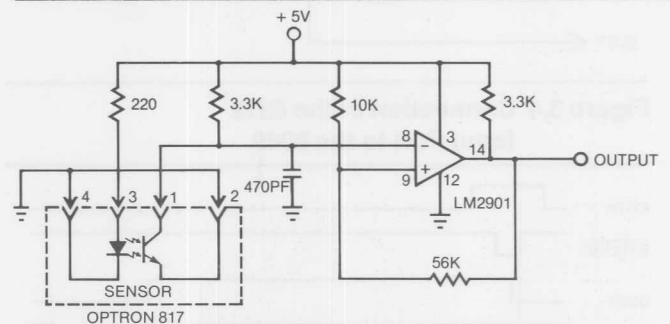
circuit is used to drive the line feed solenoid except that the current limiting resistor R2 is eliminated. This resistor is not needed because the line feed solenoid is physically much larger than the print head solenoids and can tolerate much higher levels of current.

The print head drivers are connected to an 8212 latch. The latch is interfaced to the BUS PORT on the 8049 and is enabled whenever the WR pin and the BIT 4 of PORT 1 are coincidentally low. The line feed driver is connected to PORT 1 BIT 1 of the 8049.

Note that the driver is simply a Darlington transistor that is driven by an open collector TTL gate. Resistor R2 is the current limiting resistor and diode D, capacitor C, and resistor R3 are used to "dampen" the inductive spike that occurs when driving solenoid S. This circuit is repeated for each of the seven solenoids in the print head. It should be mentioned that, although the type of Darlington transistor needed to drive the print head is not critical, a collector current rating of at least 5 amps and a breakdown voltage (Vceo) of at least 100 volts is needed. Transistors that do not meet these requirements will be damaged by the inductive kickback of the solenoids.

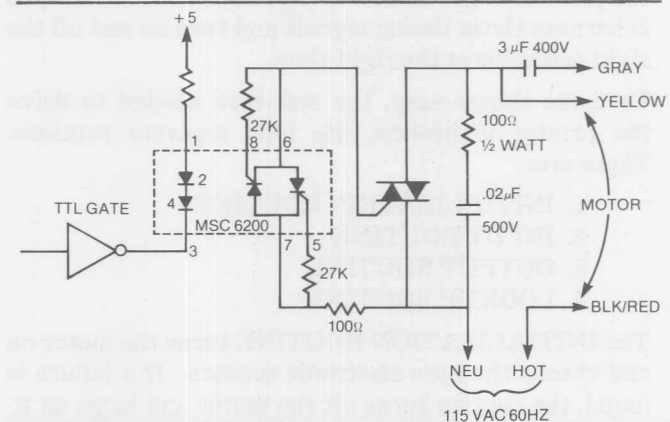
As mentioned in Section 2, the printer provides some sensor interface signals that are derived via three optoelectronic sensors. These signals must be amplified

and converted to TTL levels in order to interface to the controller. This conversion is accomplished with a simple voltage comparator. Figure 3.2 is a schematic of the sensor interface circuitry. Note that hysteresis is employed on the voltage comparators. This eliminates "false" sensing.



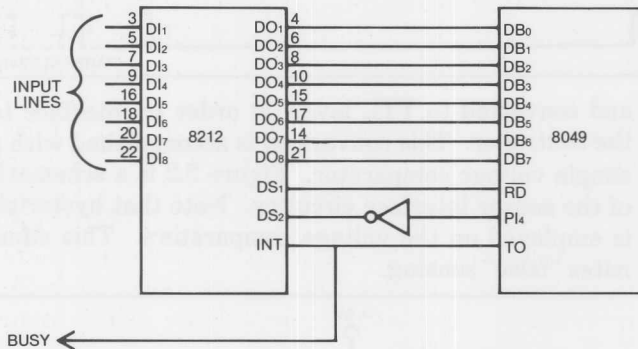
**Figure 3.2 Example of Sensor Circuit**

Motor control is accomplished by using a Monsanto MCS-6200 optically-coupled TRIAC. This part is ideal in this kind of application because it provides a simple means of controlling a line-operated motor without sacrificing the isolation needed for safe and reliable operation. Figure 3.3 is a schematic of the motor driving circuit.

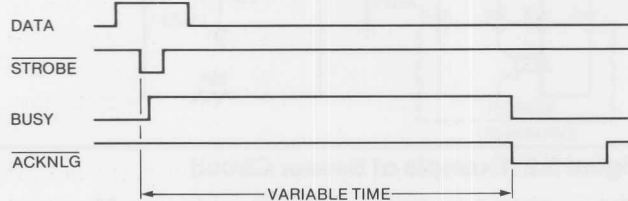


**Figure 3.3 Motor Driving Circuit**

To interface 8049 to the outside world one 8212 latch was used. This latch was connected to the BUS PORT and is enabled by an INS or MOVX instruction coincident with BIT 4 of PORT 1 being in a logical zero state. In this configuration, the 8212 was used to hold the data until read by the 8049. The connection of the 8212 to the 8049 is shown in Figure 3.4 and the parallel port timing diagram is shown in Figure 3.5. The 8212 parallel port was connected to the LINE PRINTER OUTPUT of an INTELLEC MICROCOMPUTER DEVELOPMENT SYSTEM.



**Figure 3.4** Connection of the 8212 Input Port to the 8049



**Figure 3.5** Parallel Port Timing

#### IV. SOFTWARE

As mentioned in Section 2, the bulk of the timing needed to control the printer is actually generated by the printer itself. Therefore, all the software must do is harness these timing signals and turn on and off the right solenoids at the right time.

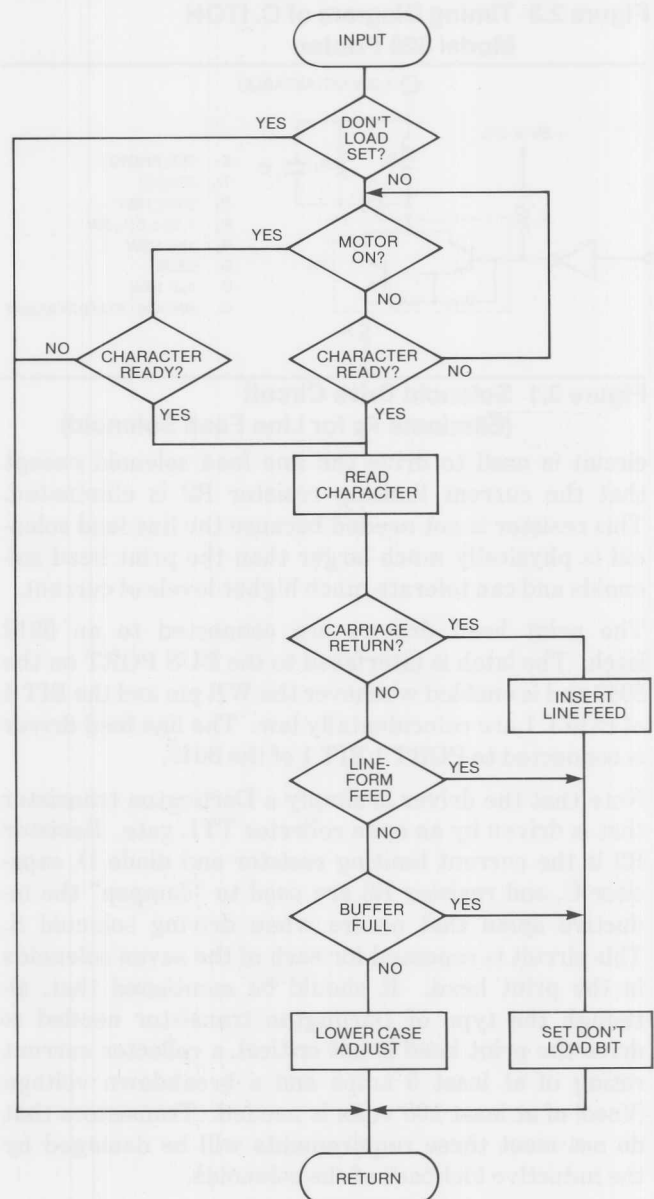
To make things easy, the software needed to drive the printer is broken into four separate routines. These are:

1. INITIALIZATION ROUTINE
2. INPUT ROUTINE
3. OUTPUT ROUTINE
4. LOOKUP ROUTINE

The INITIALIZATION ROUTINE turns the motor on and checks the opto-electronic sensors. If a failure is found, the routine turns off the motor and loops on itself. This insures that the print mechanism is cycled properly before characters are accepted for printing.

This routine also initializes all of the variables used by the printer.

The INPUT ROUTINE reads the characters that are present in the 8212 input port and writes them into the 8049's buffer memory. The routine then checks the characters to see if a CARRIAGE RETURN (ASCII OCH) has been transmitted. If a CR is detected, the input routine automatically inserts a LINE FEED as the next character. When the input routine detects a LINE FEED, it stops reading characters and sets the direction bits and the print bit in the status register. This action evokes the OUTPUT ROUTINE. A detailed flowchart of the INPUT ROUTINE is shown in Figure 4.1.



**Figure 4.1** Input Routine Flowchart

The OUTPUT ROUTINE initializes both the input and output buffer pointers and then reads the characters from the 8049's buffer memory. After a character is read the OUTPUT ROUTINE calls the LOOKUP ROUTINE which reads the proper bit pattern to form that character. This bit pattern is then used to strobe the solenoids. After each character is printed, the OUTPUT ROUTINE calls the INPUT ROUTINE and another character is placed into the buffer memory. This type of operation guarantees that the input buffer cannot "overflow" the output buffer. A flowchart of the OUTPUT ROUTINE is shown in Figure 4.2.

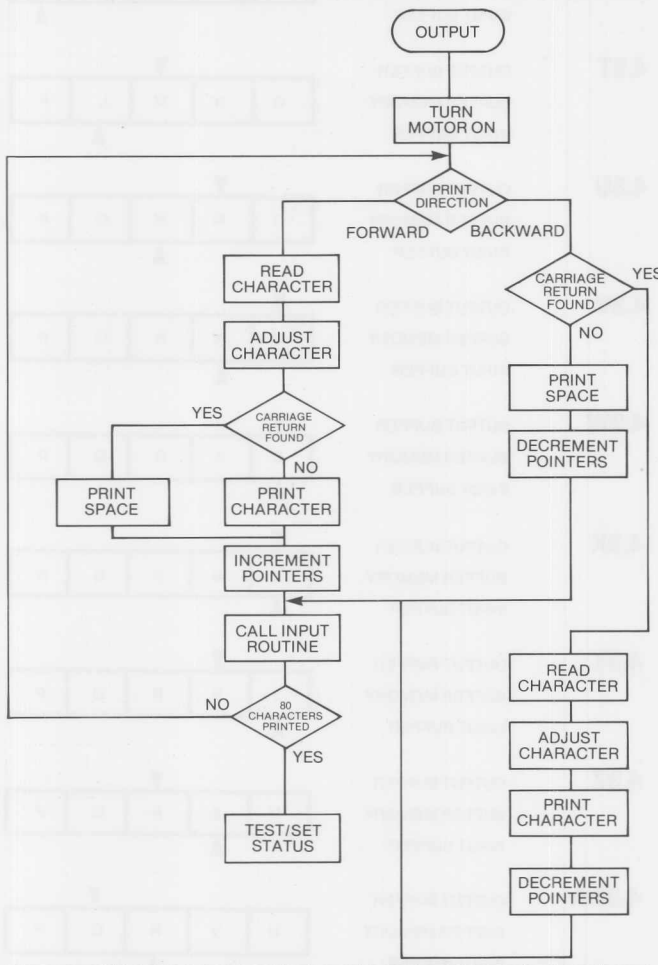


Figure 4.2 Output Routine Flowchart

#### IV-I. HANDLING THE I/O BUFFER

Since the C. ITOH Model 820 printer is capable of printing in both directions the 80 character buffer must be manipulated in a manner as to allow maximum input-output efficiency. This is accomplished by reversing the "direction" of the buffer memory each time the printer is printing from right to left. For simplicity, if it is assumed that the buffer is only five bytes long, Figure 4.3 can be used to help explain the buffer operation.

Initially the input buffer pointer is loaded with the address of the first location in the buffer memory. As characters are read, the input buffer pointer increments and fills the buffer memory as shown in Figure 4.3(b) through 4.3(f). When a CARRIAGE RETURN-LINE FEED (CRLF) is encountered the input buffer pointer and the output buffer pointer are reset back to the first location. The OUTPUT ROUTINE then reads the character from the first location in the buffer memory, increments the output buffer pointer and calls the INPUT ROUTINE, which reads another character from the parallel input port.

The OUTPUT ROUTINE reads the entire buffer, inserting space codes (20H) after a CR is detected, and the input buffer pointer follows the output buffer pointer as they "increment" up to the buffer memory. When the OUTPUT ROUTINE has printed the last character or space, the output buffer pointer and the input buffer pointer are set to point at the last location of the buffer memory. The OUTPUT ROUTINE then reads the character from the last location of the buffer memory and proceeds to "decrement" down the buffer memory. Space codes are inserted until a CR is found. Figure 4.3(1) to 4.3(0).

The input buffer pointer follows the output buffer pointer just as in the previous case. When the last, or in this case the first character is printed, the output buffer pointer and the input buffer pointer are set to point at the last location of the buffer memory. Now the pointers are "decrementing" down the buffer memory, but the printer is actually printing in a "normal" left to right fashion.

When the last character or space is printed, the output buffer and the input buffer pointer are set to the first location of the buffer memory and printing takes place in a reverse or right to left manner. After this line is printed, the print head and both buffer pointers are in the same position as they were initially. So, four lines must be printed before the buffer pointers and the print head complete a cycle. Each of these situations is handled separately by four different sub-routines: CASE0, CASE1, CASE2, and CASE3.

#### IV-II. TIMING

All critical timing for the printer controller came from two basic sources; the timing sensors on the printer and the internal eight-bit timer of the 8049.

The internal timer of the 8049 was used to control the length of time the solenoids were fired (600 microseconds) and was also used as a "one-shot" to align the printer. This alignment is needed to make the "backward" printing line up vertically with the normal or forward printing. The "one-shot" is used to measure the time from the last column of the last character position until the right sensor flag is covered.



Figure 4.3 I/O Buffer Handler

When the print head reverses direction and the right sensor flag is uncovered, the timer is then used to determine where to start printing in the reverse direction.

The timer and the print wheel on the printer are used to determine when to place a character. The strobe from the print wheel informs the 8049 when to fire the solenoids and the timer allows the proper spacing between the characters.

## V. CONCLUSION

Although the full speed of the 8049 was not used in this application, the high speed of the 8049 makes it possible to "fine-tune" any critical timing parameters. Additionally, the extra available CPU time could be used to add an interrupt driven keyboard and display, such as the ones discussed in AP-40, to the printer. This would allow the printer to function as a complete "terminal".

Very little attempt was made to optimize the software, but still the entire program fits easily in 1.25K of memory; 750 bytes for printer control and 500 bytes for character lookup. Adding lower case to the printer would require an additional 500 bytes of lookup table. The remaining 250 bytes should be used to add "user" features such as tabs, double width printing, etc.

The high speed of the 8049 combined with its hardware and software architecture make it an ideal choice for controlling an 80 column, bi-directional line printer. The I/O structure of the 8049 minimizes the amount of external hardware needed to control the printer and the large amount of on-board program and data memory allow quite a sophisticated control program to be implemented.

## 8



## APPENDIX B. MONITOR LISTING

LOC	OBJ	SEQ	SOURCE STATEMENT
		1	;
		2	;
		3	;
		4	THIS PROGRAM IMPLEMENTS CONTROL OF THE C. ITOM MODEL 820
		5	PRINTER. THE HARDWARE CONFIGURATION IS AS SUCH:
		6	8212 INPUT PORT ON BUS = DATA INPUT
		7	8212 OUTPUT PORT ON BUS = OUTPUT TO SOLENOID HAMMERS
		8	T1 INPUT = CHARACTER POSITIONING SENSOR ON PRINTER
		9	TB INPUT = INTERRUPT FROM 8212 INPUT PORT
		10	PORT 10 = MOTOR ON. LOW = ON
		11	PORT 11 = LINE FEED STROBE, LOW = ON
		12	PORT 16 = LEFT MARGIN SENSOR, LOW WHEN COVERED, HIGH WHEN OPEN
		13	PORT 17 = RIGHT MARGIN SENSOR, LOW WHEN COVERED, HIGH WHEN OPEN
		14	T1 = PIN 2 OF LM339, PRINT WHEEL SENSOR
		15	PORT 16 = PIN 13 OF LM339
		16	PORT 17 = PIN 14 OF LM339
		17	;
		18	;
		19	;
		20	SYSTEM EQUATES
		21	;
0000		22	INBUF EQU R0 ;POINTS AT INPUT LOCATION
0001		23	OUTBUF EQU R1 ;POINTS AT OUTPUT LOCATION
0002		24	SAVPNT EQU R2 ;STATUS FOR PRINTING
0003		25	STBCNT EQU R3 ;STROBE COUNTER
0004		26	TEMP1 EQU R4
0005		27	STATUS EQU R5 ;BIT 0 = LINE FEED SET
		28	;BIT 1 = PRINT
		29	;BIT 2 = CONTINUE
		30	;BIT 3 = CR FOUND
		31	;BIT 4 = LF FOUND
		32	;BIT 5 = LF FOUND IN PRINTING
		33	;BIT 6 = PRINT DIRECTION
		34	;0 = RIGHT TO LEFT
		35	;1 = LEFT TO RIGHT
		36	;BIT 7 = BUFFER LOAD DIRECTION
		37	;0 = FIRST TO MAX
		38	;1 = MAX TO FIRST
0006		39	LINCNT EQU R6 ;THE LINE COUNTER
0007		40	JUNK1 EQU R7
006F		41	MAX EQU 6FH ;MAX BUFFER LOCATION
0020		42	FIRST EQU 20H ;BOTTOM OF BUFFER
		43	\$EJECT

# AP-91

LOC	OBJ	SEQ	SOURCE STATEMENT
		44	;
0000		45	ORG 000H
		46	;
		47	;JUMP OVER THE INTERRUPT LOCATIONS
		48	;
0000 15		49	DIS I ;DON'T USE INTERRUPTS
0001 0400		50	JMP BGIN ;BEGIN THE PROGRAM
		51	;
000A		52	ORG 0AH
		53	;
		54	;START THE PROGRAM
		55	;
		56	;LOOP UNTIL THE BUFFER FILLS UP
		57	;
000A FD		58	PRNT: MOV A,STATUS ;GET THE STATUS
000B 3211		59	JB1 LPRNT ;IF PRINTING, CONTINUE
000D 3400		60	CALL LDBUF ;READ INTO THE BUFFER
000F 040A		61	JMP PRNT ;LOOP
		62	;
		63	;THIS ROUTINE PRINTS A LINE
		64	;IT FIRST SAVES THE STATUS
		65	;AND THEN DETERMINES WHICH DIRECTION TO PRINT
		66	;AND HOW TO MANIPULATE THE BUFFER
		67	;
0011 04C9		68	LPRNT: JMP STACHK ;GO FIX UP THE STATUS
0013 F224		69	LPRNT1: JB7 CASE23 ;JUMP TO CASE 2 AND 3
0015 0417		70	JMP CASE01 ;JUMP TO CASE 0 AND 1
		71	;
		72	;CASE01, LOADING THE BUFFER FROM FIRST TO MAX
		73	;
0017 0920		74	CASE01: MOV OUTBUF,#FIRST ;SET UP OUTBUF
0019 0820		75	MOV INBUF,#FIRST ;SET UP INBUF
001B FA		76	MOV A,SAVPNT ;GET THE SAVED STATUS
001C 94DC		77	CALL MOTON ;TURN ON THE MOTOR
001E 0252		78	JB6 CASE1 ;PRINT FOWARD
0020 94B3		79	CALL PRNTBK ;GET READY TO PRINT BACKWARDS
0022 0431		80	JMP CASE0 ;PRINT BACKWARDS
		81	;
		82	;CASE23, LOADING BUFFER FROM MAX TO FIRST
		83	;
0024 096F		84	CASE23: MOV OUTBUF,#MAX ;SET UP OUTBUF
0026 086F		85	MOV INBUF,#MAX ;SET UP INBUF
0028 FA		86	MOV A,SAVPNT ;GET THE PRINT STATUS
0029 94DC		87	CALL MOTON ;TURN ON THE MOTOR
002B 02C2		88	JB6 CASE3 ;PRINT LEFT TO RIGHT
002D 94B3		89	CALL PRNTBK ;GET READY TO PRINT BACKWARDS
002F 040D		90	JMP CASE2 ;PRINT RIGHT TO LEFT
		91	;
		92	*EJECT

LOC	OBJ	SEQ	SOURCE STATEMENT	
0031	F1	93	CASE0: MOV A,@OUTBUF	;GET THE CHARACTER
0032	3491	94	CALL FXPRNT	;ADJUST FOR PRINTING
0034	B120	95	MOV @OUTBUF,#20H	;PUT A SPACE IN BUFFER RAM
0036	F242	96	JB7 FDC	;FOUND A CR
0038	945E	97	CALL INCTST	;UPDATE OUTBUF
003A	C6AE	98	JZ WATCHD	;WAIT FOR END
003C	BF20	99	MOV JUNK1,#20H	;GET A SPACE TO PRINT
003E	9463	100	CALL GTPRNT	;GO PRINT A SPACE
0040	B431	101	JMP CASE0	;LOOP
0042	BF20	102	FDC: MOV JUNK1,#20H	;GO PRINT THE LAST SPACE
0044	9463	103	FDC1: CALL GTPRNT	;GO PRINT A CHARACTER
0046	945E	104	CALL INCTST	;CHECK OUT BUFFER
0048	C6AE	105	JZ WATCHD	;WAIT FOR THE END
004A	F1	106	MOV A,@OUTBUF	;GET THE CHARACTER
004B	B120	107	MOV @OUTBUF,#20H	;PUT A SPACE THERE
004D	3491	108	CALL FXPRNT	;FIX THE CHARACTER UP
004F	AF	109	MOV JUNK1,A	;SAVE IT
0050	B444	110	JMP FDC1	;LOOP
		111		
		112		
		113	;CASE 1, PRINTING LEFT TO RIGHT, LOADING BUFFER FROM	
		114	;FIRST TO MAX	
		115		
0052	F1	116	CASE1: MOV A,@OUTBUF	;GET THE CHARACTER
0053	3491	117	CALL FXPRNT	;ADJUST FOR PRINTING
0055	AF	118	MOV JUNK1,A	;SAVE ACC
0056	B120	119	MOV @OUTBUF,#20H	;PUT A SPACE IN THE BUFFER
0058	F262	120	JB7 CRFOND	;FOUND A CR?
005A	9463	121	CALL GTPRNT	;GO PRINT THE CHARACTER
005C	945E	122	CALL INCTST	;CHECK THE BUFFER
005E	C675	123	JZ WATCH	;IS THE LAST CHARACTER BEING PRINTED?
0060	B452	124	JMP CASE1	;LOOP
0062	B120	125	CRFOND: MOV @OUTBUF,#20H	;PUT A SPACE IN THE BUFFER MEMORY
0064	BF20	126	MOV JUNK1,#20H	;PUT A SPACE IN TEMP LOCATION
0066	9463	127	CALL GTPRNT	;GO PRINT THE SPACE
0068	945E	128	CALL INCTST	;CHECK THE BUFFER
006A	C675	129	JZ WATCH	;LAST CHARACTER PRINTED?
006C	F1	130	MOV A,@OUTBUF	;GET THE NEXT CHARACTER
006D	3491	131	CALL FXPRNT	;ADJUST IT
006F	B462	132	JMP CRFOND	;LOOP
		133	#EJECT	

LDC	OBJ	SEQ	SOURCE STATEMENT
		134	;
		135	;THIS ROUTINE CALLS THE LINE FEED
		136	;
BB71	9478	137 DOLF:	CALL LINEFD ;STROBE LINE FEED SOLENOID
BB73	B4BA	138	JMP PRNT ;GO BACK TO THE PRINT ROUTINE
		139	;
		140	;THIS ROUTINE COMPLETES A LINE WHEN THE PRINT
		141	;HEAD IS MOVING LEFT TO RIGHT
		142	;
BB75	27	143 WATCH:	CLR A ;ZERO ACC
BB76	62	144	MOV T,A ;ZERO TIMER
BB77	55	145	STRT T ;START THE TIMER
BB78	34BB	146	CALL LDBUF ;GO READ THE LAST CHARACTER
BB7A	B9	147 LOOPW:	IN A,P1 ;EXAMIN PORT ONE
BB7B	F27A	148	JB7 LOOPW ;CHECK RIGHT HAND SENSOR
BB7D	65	149	STOP TCNT ;STOP THE TIMER
BB7E	FD	150	MOV A,STATUS ;GET THE STATUS
BB7F	5285	151	JB2 OVR1 ;JUMP IF CONTINUE IS SET
BB81	94DF	152	CALL MOTOF ;TURN MOTOR OFF
BB83	53FD	153	ANL A,#BFDH ;RESET BIT ONE
BB85	53FB	154 OVR1:	ANL A,#BFBH ;RESET CONTINUE BIT
BB87	AD	155	MOV STATUS,A ;RESTORE STATUS
BB88	FA	156	MOV A,SAVPNT ;GET THE SAVED STATUS
BB89	B271	157	JB5 DOLF ;DO A LINE FEED IF BIT IS SET
BB8B	B4BA	158	JMP PRNT ;GO BACK TO PRINT ROUTINE
		159	;
		160	;
		161	;CASE 2, PRINTING RIGHT TO LEFT, LOADING BUFFER FROM
		162	;MAX TO FIRST
		163	;
		164	;
BB8D	F1	165 CASE2:	MOV A,@OUTBUF ;GET THE CHARACTER
BB8E	3491	166	CALL FXPRNT ;ADJUST FOR PRINTING
BB90	B12B	167	MOV @OUTBUF,#2BH ;PUT A SPACE IN BUFFER RAM
BB92	F29E	168	JB7 FDCR ;FIND A CR YET
BB94	9472	169	CALL DECTST ;CHECK THE BUFFER
BB96	C6AE	170	JZ WATCHD ;IF ZERO WAIT FOR SENSOR FLAG
BB98	BF2B	171	MOV JUNK1,#2BH ;PUT SPACE IN TEMP LOCATION
BB9A	9463	172	CALL GTPRNT ;GO PRINT SPACE
BB9C	B48D	173	JMP CASE2 ;LOOP
BB9E	BF2B	174 FDCR:	MOV JUNK1,#2BH ;GET A SPACE
BBAB	9463	175 FDCR1:	CALL GTPRNT ;GO PRINT THE CHARACTER
BBA2	9472	176	CALL DECTST ;CHECK THE BUFFER
BBA4	C6AE	177	JZ WATCHD ;LEAVE IF DONE
BBA6	F1	178	MOV A,@OUTBUF ;GET A CHARACTER
BBA7	3491	179	CALL FXPRNT ;ADJUST THE CHARACTER FOR PRINTING
BBA9	AF	180	MOV JUNK1,A ;SAVE IT
BBAA	B12B	181	MOV @OUTBUF,#2BH ;PUT A SPACE WHERE THE CHARACTER WAS
BBAC	B4AB	182	JMP FDCR1 ;LOOP
		183	*EJECT

LOC	OBJ	SEQ	SOURCE STATEMENT
		184	;
		185	;THIS ROUTINE WAITS FOR THE SENSOR FLAGS TO BE COVERED
		186	;WHEN PRINTING RIGHT TO LEFT
		187	;
00AE	3400	188	WATCHD: CALL LDBUF ;GO READ THE LAST CHARACTER
00B0	B9	189	IN A,P1 ;GET SENSOR INFORMATION
00B1	D2AE	190	JB6 WATCHD ;LOOP IF SENSOR IS NOT COVERED
00B3	FD	191	MOV A,STATUS ;GET THE STATUS
00B4	52BA	192	JB2 OVR ;SEE IF CONTINUE IS SET
00B6	94DF	193	CALL MOTOF ;TURN THE MOTOR OFF
00B8	53FD	194	ANL A,#BFDH ;RESET BIT 1
00BA	53FB	195	OVR: ANL A,#BFBH ;RESET BIT 3
00BC	AD	196	MOV STATUS,A ;RESTORE STATUS
00BD	FA	197	MOV A,SAVPNT ;GET THE SAVED STATUS
00BE	B271	198	JB5 DOLF ;ADD A LINE FEED
00CB	B40A	199	JMP PRNT ;EXIT
		200	;
		201	;CASE 3, PRINTING LEFT TO RIGHT, LOADING BUFFER FROM
		202	;MAX TO FIRST
		203	;
00C2	F1	204	CASE3: MOV A,@OUTBUF ;GET A CHARACTER
00C3	3491	205	CALL FXPRNT ;FIX FOR PRINTING
00C5	AF	206	MOV JUNK1,A ;SAVE CHARACTER
00C6	B12B	207	MOV @OUTBUF,#20H ;PUT A SPACE IN THE BUFFER
00C8	F2D2	208	JB7 CRFND ;LEAVE IF A CR IS FOUND
00CA	9463	209	CALL GTPRNT ;GO PRINT THE CHARACTER
00CC	9472	210	CALL DECTST ;CHECK THE BUFFER
00CE	C675	211	JZ WATCH ;LEAVE IF DONE
00D0	B4C2	212	JMP CASE3 ;LOOP
00D2	B12B	213	CRFND: MOV @OUTBUF,#20H ;PUT A SPACE IN THE BUFFER RAM
00D4	BF2B	214	MOV JUNK1,#20H ;GET A SPACE
00D6	9463	215	CALL GTPRNT ;PRINT A SPACE
00D8	9472	216	CALL DECTST ;CHECK THE BUFFER
00DA	C675	217	JZ WATCH ;LEAVE IF DONE
00DC	F1	218	MOV A,@OUTBUF ;GET NEXT CHARACTER
00DD	3491	219	CALL FXPRNT ;ADJUST IT
00DF	B4D2	220	JMP CRFND ;LOOP
		221	*EJECT

LOC	OBJ	SEQ	SOURCE STATEMENT	
B100		222	ORG 100H	
		223	;	
B100 B9		224	LDBUF: IN A,P1	:READ PORT 1
B101 B21C		225	JB5 LNMODE	:BIT 5 = H = LINE MODE
B103 1207		226	JB0 ARND	:JUMP AROUND IF MOTOR IS ON
B105 0901		227	ORL P1,#01H	:TURN THE MOTOR OFF
B107 920F		228	ARND: JB4 NOFF	:NO FORM FEED
B109 FE		229	MOV A,LINCNT	:GET THE LINE COUNTER
B10A 438B		230	ORL A,#8BH	:SET MSB
B10C AE		231	MOV LINCNT,A	:RESTORE THE LINE COUNTER
B10D 23FF		232	MOV A,#BFFH	:SET ACC
B10F 721A		233	NOFF: JB3 NOLF	:JUMP IF NO LINE FEED
B111 9478		234	CALL LINEFD	:GO DO A LF OR FF
B113 09		235	BUTLOP: IN A,P1	:READ THE PORT
B114 721A		236	JB3 NOLF	:WAIT FOR SWITCH TO BE RELEASED
B116 921A		237	JB4 NOLF	:WAIT FOR SWITCH TO BE RELEASED
B118 2413		238	JMP BUTLOP	:LOOP
B11A 240B		239	NOLF: JMP LDBUF	:LOOP
		240	;	
		241	;	
		242	;	
B11C 261F		243	LNMODE: JNTB CHAR	:IF CHARACTER PRESENT, READ IT
B11E 83		244	RET	:IF NOT, EXIT ROUTINE
		245	;	
		246	;	
		247	;	
B11F FD		248	CHAR: MOV A,STATUS	:GET THE STATUS
B120 5249		249	JB2 ARNDJP	:IF CONTINUE IS SET, DON'T LOAD
B122 9249		250	JB4 ARNDJP	:IF LF IS SET, DON'T LOAD
B124 724A		251	JB3 LFCRCK	:IF CR SET, SEE IF NEXT CHAR IS LF
B126 9406		252	CALL GTCAR	:GO READ A CHARACTER
B128 3461		253	GOOD: CALL FXCHAR	:MAKE SURE IT IS OK
B12A AB		254	MOV INBUF,A	:SAVE CHARACTER IN BUFFER MEMORY
B12B FD		255	MOV A,STATUS	:GET THE STATUS
B12C F239		256	JB7 SUB1	:IF BIT 7 IS SET DECREMENT BUFFER
B12E 18		257	INC INBUF	:UPDATE INBUF
B12F 237B		258	MOV A,#MAX+1	:GET TOP
B131 D8		259	XRL A,INBUF	:ARE WE AT THE TOP?
B132 9649		260	JNZ ARNDJP	:IF NOT GET THE STATUS
B134 F8		261	MOV A,INBUF	:GET INBUF
B135 07		262	DEC A	:CHANGE BY ONE
B136 AB		263	MOV INBUF,A	:PUT IT BACK
B137 2449		264	JMP ARNDJP	:GET THE STATUS
B139 F8		265	SUB1: MOV A,INBUF	:GET INBUF
B13A 07		266	DEC A	:CHANGE BY ONE
B13B AB		267	MOV INBUF,A	:PUT INBUF BACK
B13C 231F		268	MOV A,#FIRST-1	:GET THE BOTTOM OF THE BUFFER
B13E D8		269	XRL A,INBUF	:TEST THE BUFFER
B13F 9649		270	JNZ ARNDJP	:IF NOT ZERO READ THE STATUS
B141 18		271	INC INBUF	:MOVE INBUF BACK
B142 2449		272	JMP ARNDJP	:GO GET STATUS
B144 FD		273	GETSTA: MOV A,STATUS	:GET THE STATUS
B145 1249		274	JB0 ARNDJP	:IF BIT 0 SET, BYPASS
B147 925B		275	JB4 STBIT1	:IF LF IS FOUND, SET THE STATUS
B149 83		276	ARNDJP: RET	:EXIT
		277	;	
		278	;	
		279	;	
B14A 9406		280	LFCRCK: CALL GTCAR	:READ A CHARACTER
B14C 230A		281	MOV A,#0AH	:GET A LINE FEED
B14E 2428		282	JMP GOOD	:JUMP BACK
		283	;	
		284	;	
		285	;	
B150 FD		286	STBIT1: MOV A,STATUS	:LOAD THE STATUS
B151 3259		287	JB1 STPRNT	:IF STILL PRINTING, LEAVE
B153 4302		288	ORL A,#02H	:SET PRINT BIT
B155 0348		289	ADD A,#40H	:UPDATE POSITION COUNTER
B157 AD		290	MOV STATUS,A	:PUT STATUS BACK
B158 83		291	RET	:EXIT ROUTINE
B159 526B		292	STPRNT: JB2 BYEBYE	:CHECK CONTINUE BIT
B15B 4304		293	ORL A,#04H	:SET CONTINUE BIT
B15D 0348		294	ADD A,#40H	:UPDATE PRINT DIRECTION
B15F AD		295	MOV STATUS,A	:PUT THE STATUS BACK
B160 83		296	BYEBYE: RET	:EXIT
		297	;	

LDC	OBJ	SEQ	SOURCE STATEMENT
		298	;THIS ROUTINE "CONVERTS" LOWER CASE LETTERS TO
		299	;UPPER CASE
		300	;
0161	97	301	FIXCHAR: CLR C ;CLEAR THE CARRY
0162	537F	302	ANL A,#7FH ;STRIP MSB
0164	AF	303	MOV JUNK1,A ;SAVE ACC
0165	03AB	304	ADD A,#0ABH ;SEE IF NUMBER IS 6BH
0167	E67B	305	JNC FINE ;IF CARRY ISN'T SET, JUMP
0169	FF	306	MOV A,JUNK1 ;GET ACC BACK
016A	37	307	CPL A ;SUBTRACT 2BH FROM THE ACC
016B	032B	308	ADD A,#2BH
016D	37	309	CPL A
016E	2474	310	JMP FIXDUN ;JUMP TO TEST CR LF
017B	37	311	FINE: CPL A ;NOW SUBTRACT ABH FROM ACC
0171	03AB	312	ADD A,#0ABH
0173	37	313	CPL A
0174	AF	314	FIXDUN: MOV JUNK1,A ;SAVE A
0175	D3BD	315	XRL A,#BDH ;IS CHARACTER A CR
0177	967F	316	JNZ LFTEST ;IF IT IS NOT TEST LF
0179	FD	317	MOV A,STATUS ;GET THE STATUS
017A	430B	318	ORL A,#0BH ;SET BIT 3
017C	AD	319	MOV STATUS,A ;RESTORE THE STATUS
017D	248F	320	JMP FIXFIN ;LEAVE
017F	FF	321	LFTEST: MOV A,JUNK1 ;GET CHARACTER BACK
0180	D3BA	322	XRL A,#BAH ;IS IT A LF
0182	C6B9	323	JZ FIXUP ;IF ITS NOT, WE ARE DONE
0184	FF	324	MOV A,JUNK1 ;GET THE CHARACTER BACK
0185	D3BC	325	XRL A,#BCH ;IS IT A FORM FEED
0187	96BF	326	JNZ FIXFIN ;IF NOT FORM FEED, JUMP
0189	FD	327	FIXUP: MOV A,STATUS ;GET THE STATUS
018A	431B	328	ORL A,#1BH ;SET BIT 4
018C	AD	329	MOV STATUS,A ;RETURN THE STATUS
018D	345B	330	CALL STBIT1 ;SET THE STATUS
018F	FF	331	FIXFIN: MOV A,JUNK1 ;GET THE CHARACTER
LDC	OBJ	SEQ	SOURCE STATEMENT
0190	03	332	RET ;EXIT FIXCHAR
		333	;
		334	;THIS ROUTINE RECOGNIZES A LF, FF, AND CR
		335	;DURING THE PRINT OPERATION
		336	;IT ALSO FORCES A SPACE IF A CHARACTER FOUND
		337	;IN THE BUFFER IS NOT IN THE LOOKUP TABLE
		338	;
0191	AF	339	FXPRNT: MOV JUNK1,A ;SAVE ACC
0192	D3BC	340	XRL A,#BCH ;FORM FEED
0194	C6B2	341	JZ FFFIX ;GO SET FORM FEED
0196	FF	342	MOV A,JUNK1 ;RESTORE CHARACTER
0197	D3BD	343	XRL A,#BDH ;SEE IF IT IS A CR
0199	C6AB	344	JZ CRFIX ;LEAVE IF IT IS
019B	FF	345	MOV A,JUNK1 ;GET ACC BACK
019C	D3BA	346	XRL A,#BAH ;SEE IF IT IS A LF
019E	C6AB	347	JZ LFFIX ;LEAVE IF IT IS
01A0	FF	348	MOV A,JUNK1 ;GET CHARACTER BACK
01A1	53EB	349	ANL A,#EBBH ;SEE IF IT IS A CHARACTER
01A3	96BD	350	JNZ ISCHAR ;IF IT IS JUMP
01A5	232B	351	MOV A,#2BH ;PUT A SPACE IN ACC
01A7	03	352	RET ;EXIT
01A8	430B	353	CRFIX: ORL A,#0BH ;SET BIT 7
01AA	03	354	RET ;EXIT
01AB	FD	355	LFFIX: MOV A,STATUS ;GET THE STATUS
01AC	432B	356	ORL A,#2BH ;SET LF BIT IN STATUS
01AE	AD	357	MOV STATUS,A ;PUT THE STATUS BACK
01AF	232B	358	MOV A,#2BH ;GET A SPACE
01B1	03	359	RET ;EXIT
01B2	FD	360	FFFIX: MOV A,STATUS ;GET THE STATUS
01B3	432B	361	ORL A,#2BH ;SET LINE FEED BIT
01B5	AD	362	MOV STATUS,A ;PUT THE STATUS BACK
01B6	FE	363	MOV A,LINCNT ;GET THE LINE COUNT
01B7	438B	364	ORL A,#8BH ;SET BIT 7
01B9	AE	365	MOV LINCNT,A ;PUT LINE COUNT BACK
01BA	232B	366	MOV A,#2BH ;GET A SPACE
01BC	03	367	RET ;EXIT
01BD	FF	368	ISCHAR: MOV A,JUNK1 ;GET CHARACTER BACK
01BE	533F	369	ANL A,#3FH ;STRIP THE TWO MSB
01CB	03	370	RET ;EXIT

LOC	OBJ	SEQ	SOURCE STATEMENT
		371	;
		372	;THIS ROUTINE PRINTS THE CHARACTER IN THE ACC
		373	;
B1C1 AC		374 PRNTIT: MOV	TEMP1,A ;SAVE CHARACTER
B1C2 E7		375 RL	A ;MULTIPLY BY TWO
B1C3 E7		376 RL	A ;MULTIPLY BY FOUR
B1C4 6C		377 ADD	A,TEMP1 ;ADD ONCE TO MULTIPLY BY 5
		378	;
		379	;NOW SEE WHAT PART OF THE LOOKUP TABLE TO USE
		380	;
B1C5 2C		381 XCH	A,TEMP1 ;PUT CHARACTER IN A, TARGET IN TEMP1
B1C6 B2CA		382 JB5	SHORT ;JUMP TO HIGH ADDRESS IF BIT 5 SET
B1C8 44AB		383 JMP	PAGE1 ;GO TO FIRST PART OF LOOKUP TABLE
B1CA 64AB		384 SHORT: JMP	PAGE2 ;GO TO SECOND PAGE OF LOOKUP TABLE
		385	;
		386	;THIS ROUTINE TRIGGERS THE SOLENOIDS FOR 600 MICROSECONDS
		387	;AFTER WAITING FOR THE TRIGGER SIGNAL FROM THE PRINTER
		388	;
B1CC AF		389 FIRE: MOV	JUNK1,A ;SAVE THE ACC
B1CD FD		390 MOV	A,STATUS ;GET THE STATUS
B1CE D2D4		391 JB6	NT1 ;SEE IF FORWARD OR BACKWARDS
B1DB 56DB		392 FIREX: JTF	FIREX ;WAIT FOR T1
B1D2 24D6		393 JMP	FIREY ;LEAVE
B1D4 46D4		394 NT1: JNT1	NT1 ;LOOP
B1D6 FF		395 FIREY: MOV	A,JUNK1 ;GET ACC BACK
B1D7 9B		396 MOVX	PRB,A ;TRIGGER THE SOLENOID
		397	;
		398	;NOW KILL 600 MICROSECONDS
		399	;
B1DB 23F3		400 MOV	A,#BF3H ;LOAD DELAY NUMBER
B1DA 62		401 MOV	T,A ;PUT IT IN TIMER
B1DB 55		402 STRT	T ;START THE TIMER
B1DC 16EB		403 TSJTF: JTF	KTDUN ;LOOP ON TIMER FLAG
B1DE 24DC		404 JMP	TSJTF ;
B1EB 27		405 KTDUN: CLR	A ;ZERO ACC
B1E1 9B		406 MOVX	PRB,A ;TURN OFF SOLENOIDS
B1E2 65		407 STOP	TCNT ;STOP THE TIMER
B1E3 83		408 RET	;EXIT FIRE ROUTINE
		409 \$EJECT	

LDC	OBJ	SEQ	SOURCE STATEMENT
		410	;
		411	;
		412	;
		413	THIS IS THE LOOKUP TABLE. THE MSB IS NOT USED, THE MSB - 1
		414	IS THE DOT THAT IS THE TOP OF ANY GIVEN CHARACTER AND THE
		415	LSB IS THE DOT THAT IS THE BOTTOM OF ANY GIVEN CHARACTER
		416	;
		417	;
		418	;
0200		419	ORG 200H
		420	;
0200 3E		421	TABLE1: DB 3EH ; *****
0201 41		422	DB 41H ; * * *
0202 5D		423	DB 5DH ; * * * *
0203 59		424	DB 59H ; * * * *
0204 4E		425	DB 4EH ; * * *
		426	;
0205 7C		427	DB 7CH ; *****
0206 12		428	DB 12H ; * *
0207 11		429	DB 11H ; * *
0208 12		430	DB 12H ; * *
0209 7C		431	DB 7CH ; *****
		432	;
020A 7F		433	DB 7FH ; *****
020B 49		434	DB 49H ; * * * *
020C 49		435	DB 49H ; * * * *
020D 49		436	DB 49H ; * * * *
020E 36		437	DB 36H ; * * *
		438	;
020F 3E		439	DB 3EH ; *****
0210 41		440	DB 41H ; * *
0211 41		441	DB 41H ; * *
0212 41		442	DB 41H ; * *
0213 22		443	DB 22H ; * *
		444	;
0214 7F		445	DB 7FH ; *****
0215 41		446	DB 41H ; * *
0216 41		447	DB 41H ; * *
0217 41		448	DB 41H ; * *
0218 3E		449	DB 3EH ; *****
		450	;
0219 7F		451	DB 7FH ; *****
021A 49		452	DB 49H ; * * * *
021B 49		453	DB 49H ; * * * *
021C 49		454	DB 49H ; * * * *
021D 41		455	DB 41H ; * *
		456	\$EJECT

LOC	OBJ	SEQ	SOURCE STATEMENT
		457	
021E	7F	458	DB 7FH
021F	09	459	DB 09H
0220	09	460	DB 09H
0221	09	461	DB 09H
0222	01	462	DB 01H
		463	
0223	3E	464	DB 3EH
0224	41	465	DB 41H
0225	41	466	DB 41H
0226	51	467	DB 51H
0227	71	468	DB 71H
		469	
0228	7F	470	DB 7FH
0229	08	471	DB 08H
022A	08	472	DB 08H
022B	08	473	DB 08H
022C	7F	474	DB 7FH
		475	
022D	00	476	DB 00H
022E	41	477	DB 41H
022F	7F	478	DB 7FH
0230	41	479	DB 41H
0231	00	480	DB 00H
		481	
0232	20	482	DB 20H
0233	40	483	DB 40H
0234	40	484	DB 40H
0235	40	485	DB 40H
0236	3F	486	DB 3FH
		487	
0237	7F	488	DB 7FH
0238	08	489	DB 08H
0239	14	490	DB 14H
023A	22	491	DB 22H
023B	41	492	DB 41H
		493	
023C	7F	494	DB 7FH
023D	40	495	DB 40H
023E	40	496	DB 40H
023F	40	497	DB 40H
0240	40	498	DB 40H
		499	
0241	7F	500	DB 7FH
0242	02	501	DB 02H
0243	0C	502	DB 0CH
0244	02	503	DB 02H
0245	7F	504	DB 7FH
		505	
0246	7F	506	DB 7FH
0247	04	507	DB 04H
0248	08	508	DB 08H
0249	10	509	DB 10H
024A	7F	510	DB 7FH
		511	*EJECT

LOC	OBJ	SEQ	SOURCE STATEMENT	*****	*****	*****
		512				
024B	3E	513	DB 3EH	*****		
024C	41	514	DB 41H	* * *		
024D	41	515	DB 41H	* * *		
024E	41	516	DB 41H	* * *		
024F	3E	517	DB 3EH	*****		
		518				
025B	7F	519	DB 7FH	*****		
0251	09	520	DB 09H	* * *		
0252	09	521	DB 09H	* * *		
0253	09	522	DB 09H	* * *		
0254	06	523	DB 06H	* * *		
		524				
0255	3E	525	DB 3EH	*****		
0256	41	526	DB 41H	* * *		
0257	51	527	DB 51H	* * *		
0258	21	528	DB 21H	* * *		
0259	5E	529	DB 5EH	*****		
		530				
025A	7F	531	DB 7FH	*****		
025B	09	532	DB 09H	* * *		
025C	19	533	DB 19H	* * *		
025D	29	534	DB 29H	* * *		
025E	46	535	DB 46H	* * *		
		536				
025F	26	537	DB 26H	* * *		
0260	49	538	DB 49H	* * *		
0261	49	539	DB 49H	* * *		
0262	49	540	DB 49H	* * *		
0263	32	541	DB 32H	* * *		
		542				
0264	01	543	DB 01H	* * *		
0265	01	544	DB 01H	* * *		
0266	7F	545	DB 7FH	*****		
0267	01	546	DB 01H	* * *		
0268	01	547	DB 01H	* * *		
		548				
0269	3F	549	DB 3FH	*****		
026A	40	550	DB 40H	* * *		
026B	40	551	DB 40H	* * *		
026C	40	552	DB 40H	* * *		
026D	3F	553	DB 3FH	*****		
		554				
026E	1F	555	DB 1FH	*****		
026F	20	556	DB 20H	* * *		
0270	40	557	DB 40H	* * *		
0271	20	558	DB 20H	* * *		
0272	1F	559	DB 1FH	*****		
		560				
0273	7F	561	DB 7FH	*****		
0274	20	562	DB 20H	* * *		
0275	10	563	DB 10H	* * *		
0276	20	564	DB 20H	* * *		
0277	7F	565	DB 7FH	*****		
		566	*EJECT			

LOC	OBJ	SEQ	SOURCE STATEMENT	TRANSFORM	ADDR	LEN	OBJ
		567					
0278	63	568	DB 63H	; ** **	012	01	0000
0279	14	569	DB 14H	; * *	012	14	0000
027A	08	570	DB 08H	; *	012	17	0000
027B	14	571	DB 14H	; * *	012	17	0000
027C	63	572	DB 63H	; ** **	012	17	0000
		573					
027D	03	574	DB 03H	; **	012	41	0000
027E	04	575	DB 04H	; *	012	00	0000
027F	78	576	DB 78H	; ****	012	00	0000
0280	04	577	DB 04H	; *	012	00	0000
0281	03	578	DB 03H	; **	012	10	0000
		579					
0282	61	580	DB 61H	; ** *	012	00	0000
0283	51	581	DB 51H	; * * *	012	17	0000
0284	49	582	DB 49H	; * * *	012	10	0000
0285	45	583	DB 45H	; * * *	012	15	0000
0286	43	584	DB 43H	; * **	012	10	0000
		585					
0287	7F	586	DB 7FH	; ****	012	41	0000
0288	7F	587	DB 7FH	; ****	012	00	0000
0289	41	588	DB 41H	; * *	012	01	0000
028A	41	589	DB 41H	; * *	012	00	0000
028B	41	590	DB 41H	; * *	012	07	0000
		591					
028C	02	592	DB 02H	; *	012	00	0000
028D	04	593	DB 04H	; *	012	07	0000
028E	08	594	DB 08H	; *	012	00	0000
028F	10	595	DB 10H	; *	012	00	0000
0290	20	596	DB 20H	; *	012	00	0000
		597					
0291	41	598	DB 41H	; * *	012	10	0000
0292	41	599	DB 41H	; * *	012	10	0000
0293	41	600	DB 41H	; * *	012	07	0000
0294	7F	601	DB 7FH	; ****	012	10	0000
0295	7F	602	DB 7FH	; ****	012	10	0000
		603					
0296	10	604	DB 10H	; *	012	00	0000
0297	08	605	DB 08H	; *	012	00	0000
0298	04	606	DB 04H	; *	012	00	0000
0299	08	607	DB 08H	; *	012	00	0000
029A	10	608	DB 10H	; *	012	00	0000
		609					
029B	40	610	DB 40H	; *	012	00	0000
029C	40	611	DB 40H	; *	012	00	0000
029D	40	612	DB 40H	; *	012	00	0000
029E	40	613	DB 40H	; *	012	00	0000
029F	40	614	DB 40H	; *	012	00	0000
		615	*EJECT				

LDC	OBJ	SEQ	SOURCE STATEMENT
		616	;
B2A8	B888	617	PAGE1: MOV STBCNT, #00H ;ZERO STROBE COUNTER
B2A2	FA	618	MOV A, SAYPHT ;GET DIRECTION
B2A3	37	619	CPL A ;FLIP BITS
B2A4	D2B3	620	JB6 BAKWRD ;IF BACKWARD JUMP OUT
B2A6	FC	621	LKLO: MOV A, TEMP1 ;GET THE TARGET
B2A7	A3	622	MOV A, @A ;GET THE DATA
B2A8	34CC	623	CALL FIRE ;STROBE THE SOLENOIDS
B2AA	1C	624	INC TEMP1 ;INCREMENT THE POINTER
B2AB	1B	625	INC STBCNT ;INCREMENT THE STROBE COUNTER
B2AC	FB	626	MOV A, STBCNT ;GET THE STROBE COUNTER
B2AD	D3B5	627	XRL A, #05H ;IS IT FIVE
B2AF	96A6	628	JNZ LKLO ;REPEAT IF NOT FIVE
B2B1	84AE	629	JMP SETTIN ;GO BACK
B2B3	FC	630	BAKWRD: MOV A, TEMP1 ;GET THE TARGET
B2B4	B3B4	631	ADD A, #04H ;COMPENSATE FOR GOING BACKWARDS
B2B6	AC	632	MOV TEMP1, A ;SAVE IT
B2B7	FC	633	LKLO1: MOV A, TEMP1 ;GET THE TARGET
B2B8	A3	634	MOV A, @A ;GET THE DATA
B2B9	34CC	635	CALL FIRE ;STROBE THE SOLENOIDS
B2BB	FC	636	MOV A, TEMP1 ;GET TEMP1
B2BC	B7	637	DEC A ;DECREASE BY ONE
B2BD	AC	638	MOV TEMP1, A ;PUT IT BACK
B2BE	1B	639	INC STBCNT ;INCREMENT THE STROBE COUNTER
B2BF	FB	640	MOV A, STBCNT ;GET THE STROBE COUNTER
B2C8	D3B5	641	XRL A, #05H ;IS IT FIVE
B2C2	96B7	642	JNZ LKLO1 ;REPEAT IF NOT FIVE
B2C4	84AE	643	JMP SETTIN ;GO BACK, CHARACTER IS DONE
		644	*EJECT

LDC	OBJ	SEQ	SOURCE STATEMENT
		645	;
0300		646	ORG 300H
		647	;
		648	
0300	00	649	DB 00H
0301	00	650	DB 00H
0302	00	651	DB 00H
0303	00	652	DB 00H
0304	00	653	DB 00H
		654	
0305	00	655	DB 00H
0306	00	656	DB 00H
0307	5F	657	DB 5FH
0308	00	658	DB 00H
0309	00	659	DB 00H
		660	
030A	00	661	DB 00H
030B	07	662	DB 07H
030C	00	663	DB 00H
030D	07	664	DB 07H
030E	00	665	DB 00H
		666	
030F	14	667	DB 14H
0310	7F	668	DB 7FH
0311	14	669	DB 14H
0312	7F	670	DB 7FH
0313	14	671	DB 14H
		672	
0314	24	673	DB 24H
0315	2A	674	DB 2AH
0316	7F	675	DB 7FH
0317	2A	676	DB 2AH
0318	12	677	DB 12H
		678	
0319	23	679	DB 23H
031A	13	680	DB 13H
031B	00	681	DB 00H
031C	64	682	DB 64H
031D	62	683	DB 62H
		684	
031E	36	685	DB 36H
031F	49	686	DB 49H
0320	56	687	DB 56H
0321	20	688	DB 20H
0322	50	689	DB 50H
		690	\$EJECT

LDC	OBJ	SEQ	SOURCE STATEMENT
		691	
0323	00	692	DB 00H
0324	00	693	DB 00H
0325	07	694	DB 07H
0326	00	695	DB 00H
0327	00	696	DB 00H
		697	
0328	1C	698	DB 1CH
0329	22	699	DB 22H
032A	41	700	DB 41H
032B	00	701	DB 00H
032C	00	702	DB 00H
		703	
032D	00	704	DB 00H
032E	00	705	DB 00H
032F	41	706	DB 41H
0330	22	707	DB 22H
0331	1C	708	DB 1CH
		709	
0332	22	710	DB 22H
0333	14	711	DB 14H
0334	7F	712	DB 7FH
0335	14	713	DB 14H
0336	22	714	DB 22H
		715	
0337	00	716	DB 00H
0338	00	717	DB 00H
0339	7F	718	DB 7FH
033A	00	719	DB 00H
033B	00	720	DB 00H
		721	
033C	00	722	DB 00H
033D	40	723	DB 40H
033E	30	724	DB 30H
033F	00	725	DB 00H
0340	00	726	DB 00H
		727	
0341	00	728	DB 00H
0342	00	729	DB 00H
0343	00	730	DB 00H
0344	00	731	DB 00H
0345	00	732	DB 00H
		733	
0346	00	734	DB 00H
0347	00	735	DB 00H
0348	40	736	DB 40H
0349	00	737	DB 00H
034A	00	738	DB 00H
		739	
034B	20	740	DB 20H
034C	10	741	DB 10H
034D	00	742	DB 00H
034E	04	743	DB 04H
034F	02	744	DB 02H
		745	
0350	3E	746	DB 3EH
0351	51	747	DB 51H
0352	49	748	DB 49H
0353	45	749	DB 45H
0354	3E	750	DB 3EH
		751	
0355	00	752	DB 00H
0356	42	753	DB 42H
0357	7F	754	DB 7FH
0358	40	755	DB 40H
0359	00	756	DB 00H
		757	
035A	62	758	DB 62H
035B	51	759	DB 51H
035C	49	760	DB 49H
035D	49	761	DB 49H
035E	46	762	DB 46H
		763	
035F	21	764	DB 21H
0360	41	765	DB 41H

LOC	OBJ	SEQ	SOURCE STATEMENT			
0361	49	766	DB 49H	:	*	*
0362	40	767	DB 40H	:	*	*
0363	33	768	DB 33H	:	*	*
		769		:	*	*
0364	18	770	DB 18H	:	*	*
0365	14	771	DB 14H	:	*	*
0366	12	772	DB 12H	:	*	*
0367	7F	773	DB 7FH	:	*	*
0368	10	774	DB 10H	:	*	*
		775		:	*	*
0369	27	776	DB 27H	:	*	*
036A	45	777	DB 45H	:	*	*
036B	45	778	DB 45H	:	*	*
036C	45	779	DB 45H	:	*	*
036D	39	780	DB 39H	:	*	*
		781		:	*	*
036E	3C	782	DB 3CH	:	*	*
036F	4A	783	DB 4AH	:	*	*
0370	49	784	DB 49H	:	*	*
0371	49	785	DB 49H	:	*	*
0372	31	786	DB 31H	:	*	*
		787		:	*	*
0373	01	788	DB 01H	:	*	*
0374	71	789	DB 71H	:	*	*
0375	09	790	DB 09H	:	*	*
0376	05	791	DB 05H	:	*	*
0377	03	792	DB 03H	:	*	*
		793		:	*	*
0378	36	794	DB 36H	:	*	*
0379	49	795	DB 49H	:	*	*
037A	49	796	DB 49H	:	*	*
037B	49	797	DB 49H	:	*	*
037C	36	798	DB 36H	:	*	*
		799	\$EJECT	:	*	*

LDC	OBJ	SEQ	SOURCE STATEMENT	TRANSFORMED STATEMENT	OBJ	SEQ
		800				
037D	46	801	DB 46H	; * **		
037E	49	802	DB 49H	; * * *		
037F	49	803	DB 49H	; * * *		
0380	29	804	DB 29H	; * * *		
0381	1E	805	DB 1EH	; ****		
		806				
0382	00	807	DB 00H	;		
0383	00	808	DB 00H	;		
0384	14	809	DB 14H	; * *		
0385	00	810	DB 00H	;		
0386	00	811	DB 00H	;		
		812				
0387	00	813	DB 00H	;		
0388	40	814	DB 40H	; *		
0389	34	815	DB 34H	; * * *		
038A	00	816	DB 00H	;		
038B	00	817	DB 00H	;		
		818				
038C	00	819	DB 00H	; *		
038D	14	820	DB 14H	; * * *		
038E	22	821	DB 22H	; * * *		
038F	41	822	DB 41H	; * * *		
0390	00	823	DB 00H	;		
		824				
0391	14	825	DB 14H	; * *		
0392	14	826	DB 14H	; * *		
0393	14	827	DB 14H	; * *		
0394	14	828	DB 14H	; * *		
0395	14	829	DB 14H	; * *		
		830				
0396	00	831	DB 00H	;		
0397	41	832	DB 41H	; * *		
0398	22	833	DB 22H	; * *		
0399	14	834	DB 14H	; * *		
039A	00	835	DB 00H	; *		
		836				
039B	02	837	DB 02H	; *		
039C	01	838	DB 01H	; *		
039D	59	839	DB 59H	; * * *		
039E	05	840	DB 05H	; * *		
039F	02	841	DB 02H	; *		
		842	*EJECT			

LOC	OBJ	SEQ	SOURCE STATEMENT
03A0	0000	843	PAGE2: MOV STBCNT, #00H ;ZERO STROBE COUNTER
03A2	FA	844	MOV A, SAVPNT ;GET DIRECTION
03A3	37	845	CPL A ;FLIP BITS
03A4	02B5	846	JNB BKWRD ;IF BACKWARD JUMP OUT
03A6	FC	847	LKHI: MOV A, TEMP1 ;GET THE TARGET
03A7	036B	848	ADD A, #60H ;ADJUST THE TARGET
03A9	A3	849	MOVP A, @A ;GET THE DATA
03AA	34CC	850	CALL FIRE ;STROBE THE SOLENOIDS
03AC	1C	851	INC TEMP1 ;INCREMENT THE POINTER
03AD	1B	852	INC STBCNT ;INCREMENT THE STROBE COUNTER
03AE	FB	853	MOV A, STBCNT ;GET THE STROBE COUNTER
03AF	03B5	854	XRL A, #05H ;IS IT FIVE
03B1	96A6	855	JNZ LKHI ;REPEAT IF NOT FIVE
03B3	04AE	856	JMP SETTIM ;GO BACK
03B5	FC	857	BKWRD: MOV A, TEMP1 ;GET THE TARGET
03B6	0364	858	ADD A, #64H ;COMPENSATE FOR GOING BACKWARDS
03B8	AC	859	MOV TEMP1, A ;SAVE IT
03B9	FC	860	LKHI1: MOV A, TEMP1 ;GET THE TARGET
03BA	A3	861	MOVP A, @A ;GET THE DATA
03BB	34CC	862	CALL FIRE ;STROBE THE SOLENOIDS
03BD	FC	863	MOV A, TEMP1 ;GET TEMP1
03BE	07	864	DEC A ;DECREASE BY ONE
03BF	AC	865	MOV TEMP1, A ;PUT IT BACK
03C0	1B	866	INC STBCNT ;INCREMENT THE STROBE COUNTER
03C1	FB	867	MOV A, STBCNT ;GET THE STROBE COUNTER
03C2	03B5	868	XRL A, #05H ;IS IT FIVE
03C4	96B9	869	JNZ LKHI1 ;REPEAT IF NOT FIVE
03C6	04AE	870	JMP SETTIM ;GO BACK, CHARACTER IS DONE
		871	\$EJECT

LDC	OBJ	SEQ	SOURCE STATEMENT
		872	;
0400		873	ORG 400H
		874	;
0400 27		875	BGIN: CLR A ;ZERO ACC
0401 90		876	MOVX PR0,A ;TURN OFF THE SOLENOIDS
0402 9400		877	CALL SETUP ;SET UP THE PRINTER
0404 943F		878	CALL VARSET ;SET UP THE SOFTWARE
0406 040A		879	JMP PRNT ;GO START
		880	;
0408 23FE		881	SETUP: MOV A,#0FEH ;LOAD ACC WITH VALUE TO TURN ON MOTOR
040A 39		882	OUTL P1,A ;TURN ON MOTOR
		883	;
		884	;
		885	;
0408 BC05		886	MOV TEMP1,#05H ;LOAD DELAY VALUE ONE
040D BFFF		887	SELFC: MOV JUNK1,#0FFH ;LOAD DELAY VALUE TWO
040F BEFF		888	SELFB: MOV LINCNT,#0FFH ;LOAD DELAY VALUE THREE
0411 09		889	SELFA: IN A,P1 ;READ PORT ONE
0412 37		890	CPL A ;MAKE THINGS RIGHT
0413 F21D		891	JB7 DONE1 ;IS BIT 7 SET?
0415 EE11		892	DJNZ LINCNT,SELFA ;SMALL LOOP
0417 EBF0		893	DJNZ JUNK1,SELFB ;BIGGER LOOP
0419 EC0D		894	DJNZ TEMP1,SELFC ;BIGGEST LOOP
041B 045A		895	JMP ERROR ;SOMETHING IS WRONG
		896	;
		897	;
		898	;
		899	DDNER: MOV JUNK1,#0FFH ;SET UP DELAY
041D BFFF		900	SELF: MOV LINCNT,#0FFH ;SOME MORE DELAY
041F BEFF		901	SELF1: IN A,P1 ;GET THE FLAG INFORMATION
0421 09		902	JB7 DONEF ;IS FLAG CLEARED?
0422 F22A		903	DJNZ LINCNT,SELF1 ;IF NOT LOOP
0424 EE21		904	DJNZ JUNK1,SELF ;LOOP SOME MORE
0426 EF1F		905	JMP ERROR ;LEAVE IF FLAG IS NOT UNCOVERED
0428 045A		906	;
		907	;
		908	;
		909	;
042A BC04		910	DONEF: MOV TEMP1,#04H ;LOAD DELAY 1
042C BFFF		911	SELFCC: MOV JUNK1,#0FFH ;LOAD DELAY 2
042E BEFF		912	SELFBB: MOV LINCNT,#0FFH ;LOAD DELAY 3
0430 09		913	SELFAA: IN A,P1 ;READ THE PORT
0431 37		914	CPL A ;CHANGE THINGS AROUND
0432 D23C		915	JB6 DONE1 ;OK IF BIT 6 IS A ZERO
0434 EE30		916	DJNZ LINCNT,SELFAA ;SMALL LOOP
0436 EF2E		917	DJNZ JUNK1,SELFBB ;BIGGER LOOP
0438 EC2C		918	DJNZ TEMP1,SELFCC ;BIGGEST LOOP
043A 045A		919	JMP ERROR ;SOMETHING IS WRONG
043C 0901		920	DONE1: ORL P1,#01H ;TURN MOTOR OFF
043E 03		921	RET ;GO BACK
		922	;
		923	;
		924	;
		925	VARSET: MOV A,#0FEH ;LOAD THE TIMER
043F 23FE		926	MOV T,A
0441 62		927	STRT T ;START THE TIMER
0442 55		928	MOV INBUF,#FIRST ;LOAD INPUT BUFFER
0443 B020		929	MOV LINCNT,#00H ;SET LINE COUNT
0445 BE00		930	MOV STATUS,#00H ;SET FORWARD BIT
0447 B000		931	;
		932	;
		933	;
		934	;
0449 B920		935	CLRMEM: MOV OUTBUF,#FIRST ;LOAD OUTBUF
044B 2320		936	MOV A,#20H ;PUT SPACE CODE IN ACC
044D A1		937	MOV @OUTBUF,A ;PUT SPACE CODE IN DATA MEMORY
044E 19		938	INC OUTBUF ;UPDATE THE POINTER
044F F9		939	MOV A,OUTBUF ;MOVE THE POINTER INTO ACC
0450 D370		940	XRL A,#00H+1 ;SEE IF DONE
0452 9640		941	JNZ CLRMEM ;LOOP IF NOT CLEARED
		942	;
		943	;
		944	;
0454 99EF		945	ANL P1,#0EFH ;SET ENABLE BIT
0456 00		946	MOVX A,@INBUF ;CLEAR THE 0212 INPUT BUFFER
0457 0910		947	ORL P1,#10H ;RESET ENABLE BIT

# AP-91

LOC	OBJ	SEQ	SOURCE STATEMENT	
		948	;NOW EXIT VARSET	
		949	;	
B459	83	950	RET	;LEAVE INITIALIZATION
		951	;	
		952	;THIS ROUTINE TURNS THE MOTOR OFF AND LOOPS	
		953	;	
B45A	89FF	954	ERROR: ORL P1,#0FFH	;TURN OFF MOTOR
B45C	845C	955	DEAD: JMP DEAD	;LOOP BECAUSE SOMETHING IS WRONG
		956	;	
		957	;THESE ARE ALL SUBROUTINES THAT ARE CALLED	
		958	;	
B45E	19	959	INCTST: INC OUTBUF	;UPDATE THE POINTER
B45F	237B	960	MOV A,#MAX+1	;GET THE VALUE FOR THE LAST CHARACTER
B461	D9	961	XRL A,OUTBUF	;DO THE TEST
B462	83	962	RET	;EXIT
B463	89	963	GTPRNT: IN A,P1	;READ PORT ONE
B464	37	964	CPL A	;FLIP BITS
B465	D263	965	JB6 GTPRNT	;LOOP UNTIL SENSOR IS UNCOVERED
B467	166B	966	TSTJTF: JTF PIT	;SEE IF TIMER FLAG IS SET
B469	8467	967	JMP TSTJTF	;TEST FLAG
B46B	65	968	PIT: STOP TCNT	;STOP THE TIMER
B46C	FF	969	MOV A,JUNK1	;GET THE CHARACTER
B46D	34C1	970	CALL PRNTIT	;PRINT THE CHARACTER
B46F	341C	971	CALL LMODE	;GET ANOTHER CHARACTER
B471	83	972	RET	;EXIT
B472	F9	973	DECTST: MOV A,OUTBUF	;GET OUTBUF
B473	B7	974	DEC A	;REDUCE BY ONE
B474	A9	975	MOV OUTBUF,A	;PUT BACK IN OUTBUF
B475	D31F	976	XRL A,#FIRST-1	;SEE IF IT IS ALL THE WAY DOWN
B477	83	977	RET	;EXIT
		978	;	
		979	;THIS ROUTINE DOES A LINE FEED	
		980	;	
B478	FE	981	LINEFD: MOV A,LINCNT	;GET THE LINE COUNT
B479	F29B	982	JB7 DOFF	;IF BIT 7 IS SET, DO A FORMFEED
B47B	99FD	983	LFDO: ANL P1,#BFDH	;TURN ON THE SOLENOID
B47D	BC4D	984	MOV TEMP1,#4DH	;LOAD ONE DELAY
B47F	BF93	985	LFLP1: MOV JUNK1,#93H	;LOAD ANOTHER DELAY
B481	EF81	986	LFLP2: DJNZ JUNK1,LFLP2	;LOOP
B483	EC7F	987	DJNZ TEMP1,LFLP1	;LOOP SOME MORE
B485	89B2	988	ORL P1,#B2H	;TURN OFF LF SOLENOID
B487	1E	989	INC LINCNT	;UPDATE THE LINE COUNTER
B488	FE	990	MOV A,LINCNT	;GET THE LINE COUNT
B489	D32B	991	XRL A,#2BH	;IS PAGE DONE
B48B	96BF	992	JNZ NOTDON	;SKIP OVER
B48D	BE8B	993	MOV LINCNT,#BBH	;ZERO LINE COUNTER
		994	;	
		995	;NOW DELAY 90 MILLISECONDS	
		996	;	
B48F	BC8B	997	NOTDON: MOV TEMP1,#8BH	;LOAD DELAY VALUES
B491	BFFF	998	LOP1: MOV JUNK1,#BFFH	;
B493	EF93	999	LOP2: DJNZ JUNK1,LOP2	;GENERATE DELAY
B495	EC91	1000	DJNZ TEMP1,LOP1	;
B497	83	1001	RET	;LINE FEED IS DONE
		1002	;	
		1003	;THIS ROUTINE DOES A FORM FEED	
		1004	;	
B498	89	1005	DOFF: IN A,P1	;GET THS STATUS
B499	37	1006	CPL A	;FLIP ACC
B49A	53CB	1007	ANL A,#BCBH	;LEAVE ONLY TWO MSB'S
B49C	C69B	1008	JZ DOFF	;IF A FLAG ISN'T COVERED, LOOP
B49E	89B1	1009	ORL P1,#B1H	;TURN THE MOTOR OFF
B4A0	947B	1010	CALL LFDO	;GO DO ONE LINE FEED
B4A2	FE	1011	FFCK: MOV A,LINCNT	;GET THE LINE COUNT
B4A3	537F	1012	ANL A,#7FH	;STRIP BIT SEVEN
B4A5	D3BB	1013	XRL A,#BBH	;IS IT DONE
B4A7	C6AD	1014	JZ FFDONE	;LEAVE IF IT IS
B4A9	947B	1015	CALL LFDO	;STROBE THE SOLENOIDS
B4AB	84A2	1016	JMP FFCK	;CHECK THE FORM FEED OUT
B4AD	83	1017	FFDONE: RET	;EXIT FORM FEED
		1018	;	
B4AE	23EB	1019	SETTIM: MOV A,#BEBH	;GET DELAY VALUE
B4B0	62	1020	MOV T,A	;PUT IN TIMER
B4B1	55	1021	STR T	;START THE TIMER
B4B2	83	1022	RET	;EXIT
		1023	;	

LDC	OBJ	SEQ	SOURCE	STATEMENT	
B4B3	42	1024	PRNTBK:	MOV	A,T
B4B4	37	1025		CPL	A
B4B5	17	1026		INC	A
B4B6	17	1027		INC	A
B4B7	17	1028		INC	A
B4B8	17	1029		INC	A
B4B9	17	1030		INC	A
B4BA	62	1031		MOV	T,A
B4BB	09	1032	INLOOP:	IN	A,P1
B4BC	F2CB	1033		JB7	CONPBK
B4BE	84BB	1034		JMP	INLOOP
B4CB	55	1035	CONPBK:	STRT	T
B4C1	16C5	1036	CONPB:	JTF	RDTOPT
B4C3	84C1	1037		JMP	CONPB
B4C5	23FF	1038	RDTOPT:	MOV	A,#BFFH
B4C7	62	1039		MOV	T,A
B4C8	83	1040		RET	
		1041			
		1042			
		1043			
B4C9	FD	1044	STACHK:	MOV	A,STATUS
B4CA	92D2	1045		JB4	LFSET
B4CC	AA	1046	B4RET:	MOV	SAVPNT,A
B4CD	53C2	1047		ANL	A,#0C2H
		1048			
B4CF	AD	1049		MOV	STATUS,A
B4D0	B413	1050		JMP	LPRNT1
B4D2	432B	1051	LFSET:	ORL	A,#2BH
B4D4	84CC	1052		JMP	B4RET
		1053			
		1054			
		1055			
B4D6	99EF	1056	GTCHAR:	ANL	P1,#BEFH
B4D8	8B	1057		MOVX	A,@INBUF
B4D9	891B	1058		ORL	P1,#1BH
B4DB	83	1059		RET	
		1060			
		1061			
		1062			
B4DC	99FE	1063	MOTON:	ANL	P1,#BFEH
B4DE	83	1064		RET	
		1065			
		1066			
		1067			
B4DF	89B1	1068	MOTOF:	ORL	P1,#B1H
B4E1	83	1069		RET	
		1070			
		1071		END	

## USER SYMBOLS

ARND	B107	ARNDJP	B149	B4RET	B4CC	BAKWRD	B2B3	BGIN	B4BB	BKWRD	B3B5	BUTLOP	B113	BYEBYE	B160
CASEB	B031	CASEB1	B017	CASE1	B052	CASE2	B0B0	CASE23	B024	CASE3	B0C2	CHAR	B11F	CLRNEM	B44B
CONPB	B4C1	CONPBK	B4CB	CRFIX	B1AB	CRFND	B0D2	CRFND	B062	DEAD	B45C	DECTST	B472	DOFF	B49B
DOLF	B071	DONEF	B42A	DONEL	B43C	DONER	B41D	ERROR	B45A	FDC	B042	FDC1	B044	FDCR	B09E
FDCR1	B0AB	FFCK	B4A2	FFDDNE	B4AD	FFFIK	B1B2	FINE	B17B	FIRE	B1CC	FIREX	B1DB	FIREY	B106
FIRST	B02B	FIXDUN	B174	FIXFIN	B1BF	FIXUP	B1B9	FXCHAR	B161	FXPRNT	B191	GETSTA	B144	GOOD	B12B
GTCHAR	B4D6	GTFRNT	B463	INBUF	B0B0	INCTST	B45E	INLOOP	B4BB	ISCHAR	B1B0	JUNK1	B0B7	KTDUN	B1E0
LDBUF	B1BB	LFCRCK	B14A	LFDD	B47B	LFIFK	B1AB	LFLP1	B47F	LFLP2	B4B1	LFSET	B4D2	LFTEST	B17F
LINCNT	B0B6	LINEFD	B47B	LKHI	B3A6	LKH11	B3B9	LKLO	B2A6	LKLO1	B2B7	LNMODE	B11C	LOOPW	B07A
LOP1	B491	LOP2	B493	LPRNT	B011	LPRNT1	B013	MAX	B06F	MOTOF	B4DF	MOTON	B4DC	NOFF	B1BF
NOLF	B11A	MOTDOW	B4BF	NT1	B1D4	OUTBUF	B0B1	OVR	B0BA	OVR1	B0B5	PAGE1	B2AB	PAGE2	B3AB
PIT	B46B	PRNT	B0BA	PRNTBK	B4B3	PRNT1T	B1C1	RDTOPT	B4C5	SAVPNT	B0B2	SELF	B41F	SELF1	B421
SELF1	B411	SELF1A	B43B	SELF1B	B4BF	SELF1B	B42E	SELF1	B4B0	SELF1C	B42C	SETTIM	B4AE	SETUP	B4B8
SHORT	B1CA	STACHK	B4C9	STATUS	B0B5	STBCNT	B0B3	STBIT1	B15B	STPRNT	B159	SUB1	B139	TABLE1	B2B0
TEMP1	B0B4	TSJTF	B1DC	TSTJTF	B467	VARSET	B43F	WATCH	B075	WATCHD	B0AE				

ASSEMBLY COMPLETE, NO ERRORS

